YUCHEN WU

Toronto, Ontario, Canada +1-519-694-7627 cheneyuwu@gmail.com https://cheneyuwu.github.io/

ACADEMIC HISTORY

MASc in Aerospace Science and Engineering University of Toronto Institute for Aerospace Studies (UTIAS), Canada Supervisor: Prof. Timothy D. Barfoot Thesis: VT&R3: Generalizing the Visual Teach & Repeat Navigation Framework

BASc in Engineering Science (Robotics)

University of Toronto, Canada CGPA: 3.94 / 4.0 (High Honours) Supervisor: Prof. Florian Shkurti and Prof. Jonathan Kelly Thesis: Combining Reinforcement Learning and Imitation Learning through Reward Shaping for Continuous Control

EMPLOYMENT HISTORY

Nuro, Toronto, Canada Software Engineer Working on autonomous vehicle software for localization, mapping and sensor calibration.

Intel Corporation, Toronto, Canada

Software Engineer Intern

Worked on Intel HLS Compiler and Intel FPGA SDK for OpenCL

- Intel HLS Compiler: a high-level synthesis (HLS) tool that takes in untimed C++ code and generates productionquality register transfer level (RTL) code optimized for Intel FPGAs.
- Intel FPGA SDK for OpenCL: development environment that enables software developers to accelerate applications by targeting heterogeneous platforms with Intel CPUs and FPGAs.

SKILLS

Communication	Chinese (Mandarin), English
Programming	C/C++, Python, JavaScript, Java
Software/Libraries	MATLAB, Robot Operating System (ROS), MuJoCo, OpenCV, PyTorch, TensorFlow

PUBLICATIONS

Along Similar Lines: Local Obstacle Avoidance for Long-term Autonomous Path Following Jordy Sehn, Yuchen Wu, Timothy D. Barfoot Submitted to *IEEE International Conference on Robotics and Automation (ICRA)*, 2023

Picking Up Speed: Continuous-Time Lidar-Only Odometry using Doppler Velocity Measurements Yuchen Wu, David J. Yoon, Keenan Burnett, Soeren Kammel, Yi Chen, Heethesh Vhavle, Timothy D. Barfoot *IEEE Robotics and Automation Letters (RA-L)*, 2023

Are We Ready for Radar to Replace Lidar in All-Weather Mapping and Localization? Keenan Burnett^{*}, Yuchen Wu^{*}, David J. Yoon, Angela P. Schoellig, Timothy D. Barfoot *IEEE Robotics and Automation Letters (RA-L)*, 2022

September 2020 - November 2022

September 2015 - April 2020

May 2018 - May 2019

November 2022 - Present

Boreas: A Multi-Season Autonomous Driving Dataset

Keenan Burnett, David J. Yoon, **Yuchen Wu**, Andrew Zou Li, Haowei Zhang, Shichen Lu, Jingxing Qian, Wei-Kang Tseng, Andrew Lambert, Keith Y.K. Leung, Angela P. Schoellig, Timothy D. Barfoot Accepted by *International Journal of Robotics Research (IJRR)*

Shaping Rewards for Reinforcement Learning with Imperfect Demonstrations using Generative Models Yuchen Wu, Melissa Mozifian, Florian Shkurti IEEE International Conference on Robotics and Automation (ICRA), 2021

OPEN-SOURCE PROJECTS

Visual Teach and Repeat 3 (VT&R3)

https://github.com/utiasASRL/vtr3

• An end-to-end navigation system for long-range and long-term mobile robot path following using a lidar, radar, or camera as the primary sensor.

AWARDS

Vector Scholarship in AI, Vector Institute	2020
CRA Outstanding Undergraduate Researchers Honorable Mentions	2020
University of Toronto Dean's Honours List	2015 - 2020
University of Toronto Excellence Awards (UTEA)	2019
Garnet W. Mckee - Lachlan Gilchrist Scholarship, UofT	2017

STUDENT ACTIVITIES

UofT aUToronto Team, Student Advisor,	September 2021 - June 2022
• 1st place overall in the first competition of the four-year SAE AutoDrive Challenge	Series II.
ROB310 Mathematics for Robotics , Teaching Assistant	Fall 2021
University of Toronto, Research Assistant	May 2019 - September 2019
Supervisor: Prof. Florian Shkurti at the Department of Computer ScienceWorked on reinforcement and imitation learning for control.	
UofT Machine Intelligence Student Team, Academic Lead	September 2018 - May 2019
Built a machine learning community for undergrad students.Organized MIST101, a workshop on machine learning fundamentals.	
University of Toronto, Research Assistant	May 2017 - September 2017
Supervisor: Prof. Jianwen Zhu at the Department of Electrical and Computer EngineWorked on accelerating the training and inference of deep CNN on multi-core CPU.	neering
National University of Singapore, Research Assistant	May 2016 - July 2016
Supervisor: Prof. Shailendra Joshi at the Department of Mechanical EngineeringWorked on computational modeling and analysis of nano/micro lattice structure.	